

# The Autostigmatic Microscope and Its Uses

Presented by:



# Systems and Instrumentation Technical Group

- Our Technical Group is part of the Fabrication, Design, and Instrumentation Technical Division
- We emphasize a systems approach integrating several disciplines into an optical instrument
- Examples include telescope systems, spectroscopic instruments, commercial optics, and many others



# Systems and Instrumentation Leadership

- John D. Corless, Chair
- Fahd Banakhr, Executive Committee
- Santosh Tripathi, Executive Committee
  
- Please reach out to us (contact info in OSA member directory) with any comments or feedback about the technical group



# Systems and Instrumentation Goals

- Build community
  - <https://www.linkedin.com/groups/Systems-Instrumentation-Technical-Group-8272921/about>
  - Over 70 members so far, please join!
- Resource for members
  - Topically relevant webinars, like this one!



## Our Speaker – Robert Parks

- BA and MA in Physics from Ohio Wesleyan University and Williams College (respectively)
- Has worked at Eastman Kodak Company, Itek Corporation, and Frank Cooke, Inc.
- In 1976 he went to the Optical Sciences Center, University of Arizona, to manage the optics shop and was promoted to Assistant Research Professor
- He started Optical Perspectives Group in 1992 and is still active there



# The Autostigmatic Microscope and its Uses

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# Outline

- What is an autostigmatic microscope (ASM)
- Measuring the radius of curvature of a concave surface
  - – Main historical use
- Modern version of an ASM uses internal infinite conjugate optics
- Use of an ASM for alignment of optical systems
- Other uses of an ASM
- Conclusions



# Description of an ASM

First description in English literature is Drysdale, *Trans. Opt. Soc. London*, 1900

About two years ago, when I was endeavouring to obtain information concerning the curves of various lenses for the information of my students, I was struck with the fact that no method of easily determining the curves of such lenses was described in optical books. On enquiry in the Trade I was surprised to find that no accurate method of measuring such curves appeared to be known, and I immediately set to work to devise such a method, the result being to obtain one, which although absurdly simple in principle, appears to be very convenient in practice, and to be capable of measuring the curvature of any spherical or cylindrical surfaces, from quite shallow curves to those of less than a millimeter radius.





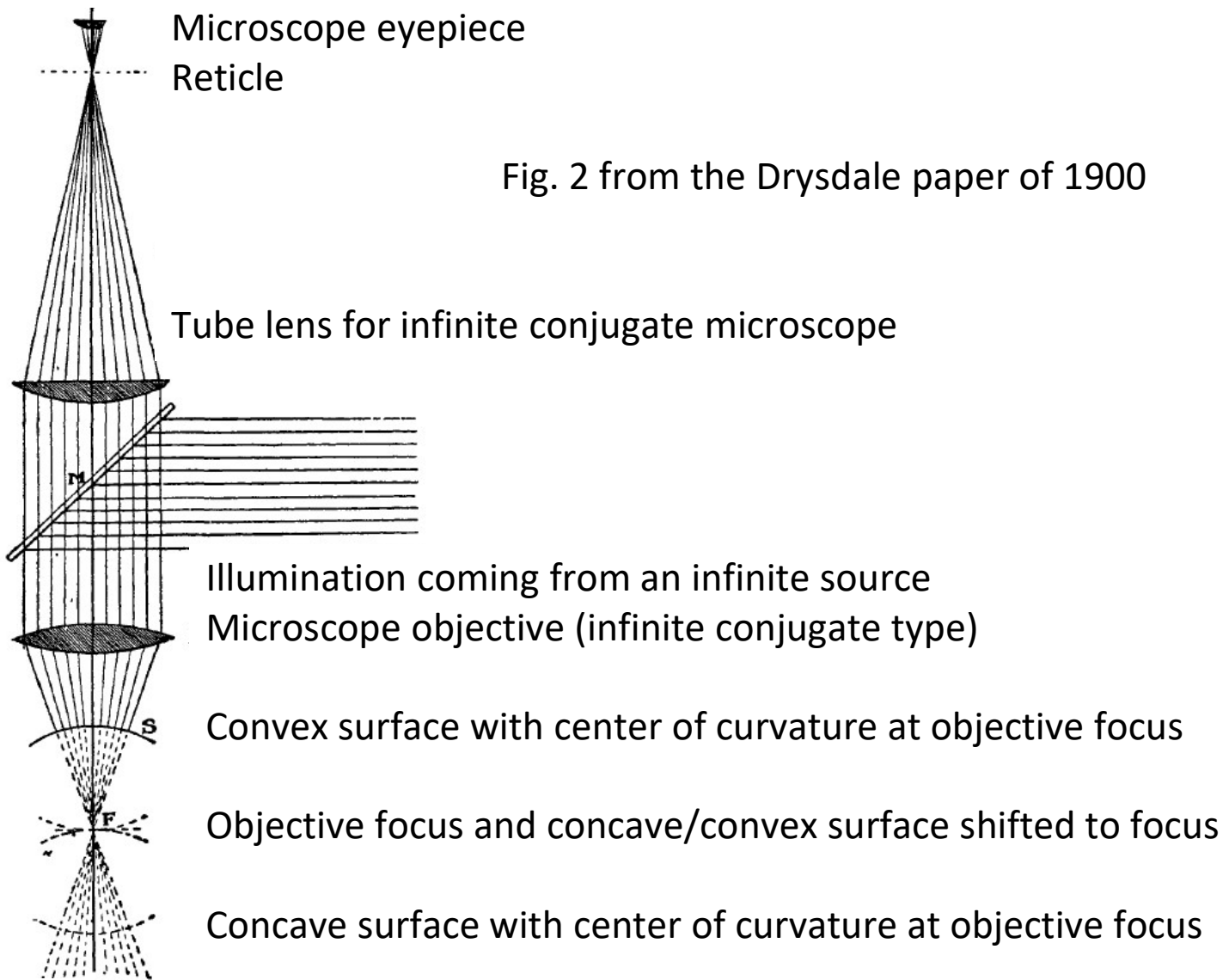
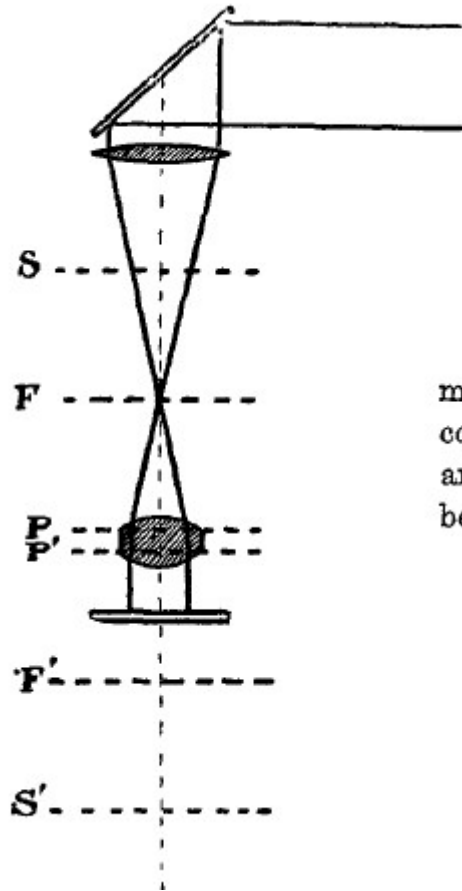


Fig. 2 from the Drysdale paper of 1900



# Further from the Drysdale paper



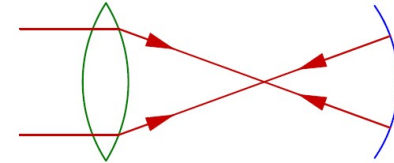
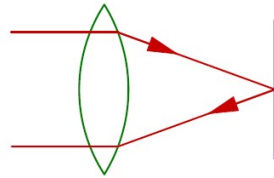
## Determination of the Optical Properties of Small Lenses.

Although the method here described is particularly convenient for measuring curvatures, it is also capable of being used with greater convenience than any other for the measurement of the focal length and other optical properties of small lenses, and a few words may not be out of place on this subject.

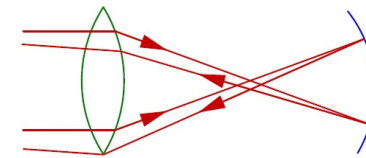
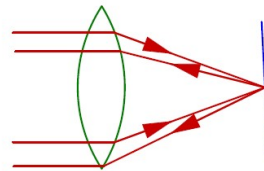


# Cat's eye and confocal foci

Surface normal to ASM axis  
or surface C of C at ASM focus



Surface tilted to ASM axis or  
ASM focus displaced from  
C of C of surface



Cat's eye reflection

Confocal reflection

Objective focused on surface  
curvature

Rays focused at center of

Out going rays re-enter on opposite  
side of objective

Rays hit surface at near normal  
incidence and re-trace themselves

If surface tilted, reflected rays parallel  
outgoing rays in collimated space

If surface tilted, rays do not re-trace  
and will not center on crosshairs

Cat's eye used for setting crosshairs

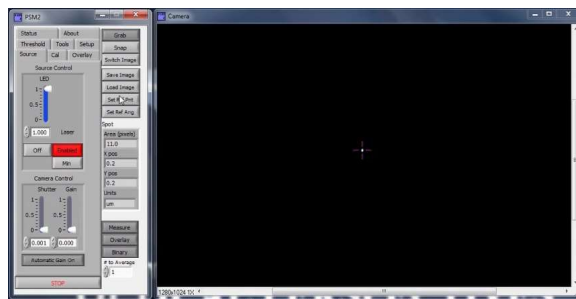
Confocal used for alignment

Cat's eye used for setting reference

Confocal for bringing CofC to reference

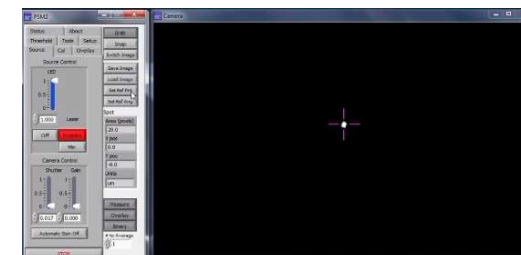
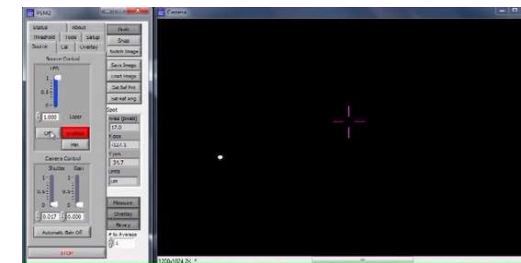
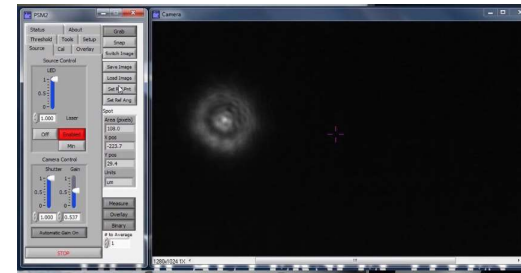


# Examples of Cat's eye and CofC spot images



Out of focus Cat's eye spot image (above)  
In focus Cat's eye (below)  
Notice Shutter and Gain with focus

Locate an ephemeral point in space with 3 degrees of freedom to  $\mu\text{m}$  precision



Out of focus & decentered CofC spot  
In focus but decentered CofC spot  
In focus and centered CofC spot

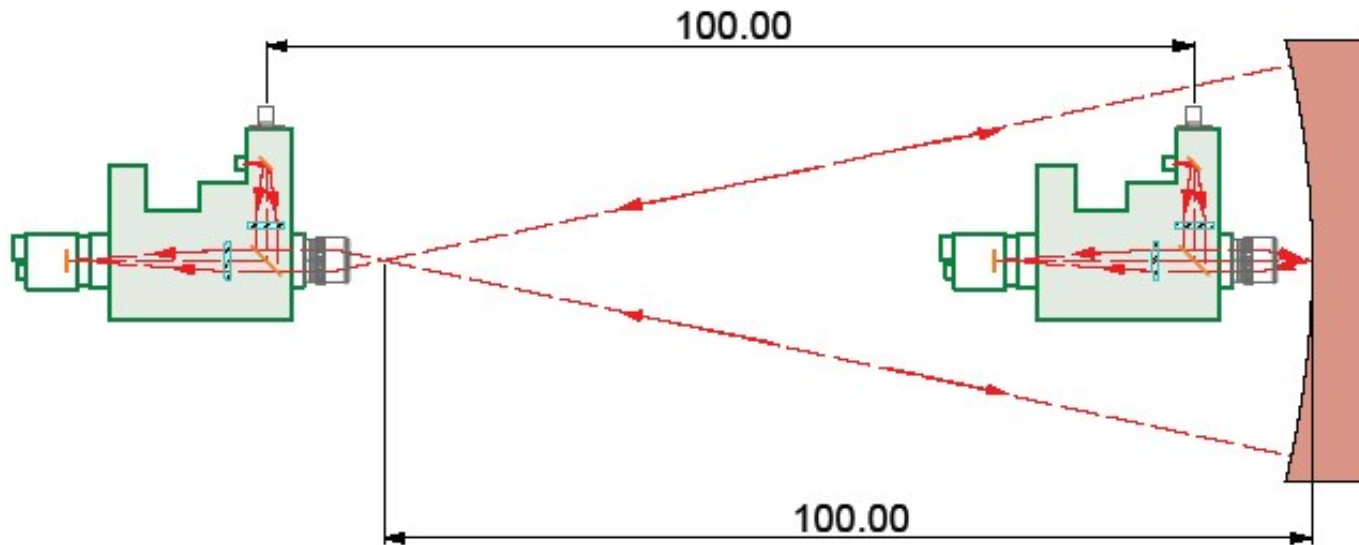
# Measurement of radius of curvature

Consists of three steps:

1. Focus on the concave mirror surface to get a Cat's eye reflection  
Set the reticle or electronic cross hairs on the reflected point image  
This established the optical axis of the ASM
2. Move the ASM back to near the center of curvature of the concave mirror  
Locate the reflected focused spot which may not be aligned to the objective  
Tilt the mirror until the reflected focused spot enters the objective  
Focus the ASM on the reflected spot and center it on the crosshairs  
Note the distance of the ASM on a linear scale
3. Move the ASM forward until it is focused on the mirror surface  
Moving from center of curvature means moving on a normal to the surface  
Get a sharp focus the Cat's eye reflection  
Cat's eye reflection will necessarily be centered on the cross hairs  
Read the distance of the ASM on the linear scale  
The difference of the Cat's eye and confocal positions is the radius of curvature of the mirror



# Measurement of radius of curvature



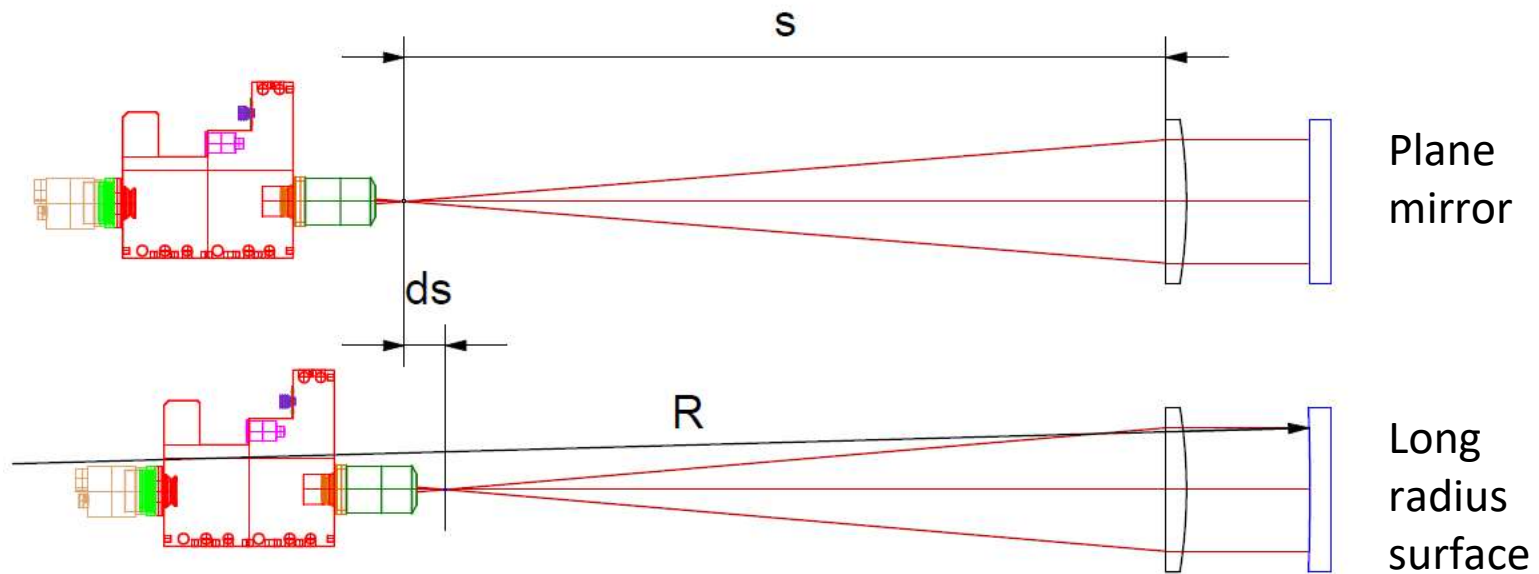
1. Focus on surface, used Cat's eye reflection to set crosshairs
2. Move to confocal, adjust microscope so reflected spot in focus and centered on crosshairs, note linear scale reading
3. Move to focus on surface and get well focused Cat's eye spot. Note scale reading  
Difference in readings is the radius of curvature

*If this concept is well understood all other applications are easy*



# Measurement of long radius of curvature

## Use defocused collimator

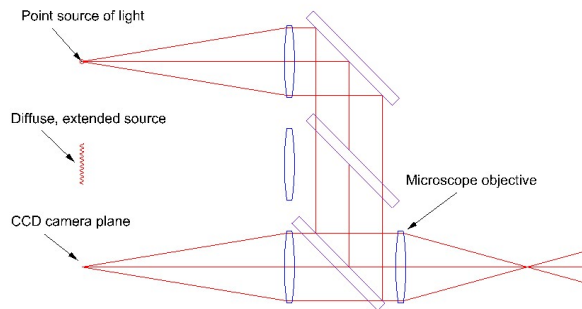


1. Find  $s$  by putting a plane mirror in front of collimator
2. Put long radius surface in front of collimator and note  $ds$
3. Since to first order  $e\text{fl} = s$ ,  $1/s = 1/(s - ds) + 1/R$ , we find  $R = -s(1 + (s/ds))$

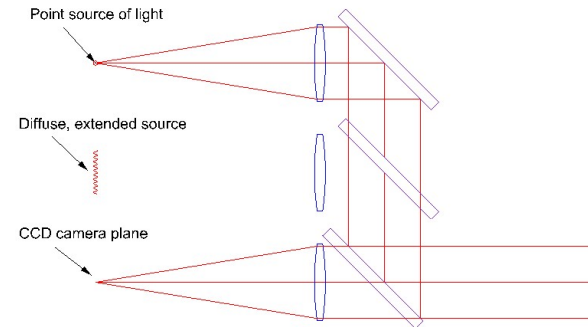
(Be careful of signs, use common sense)



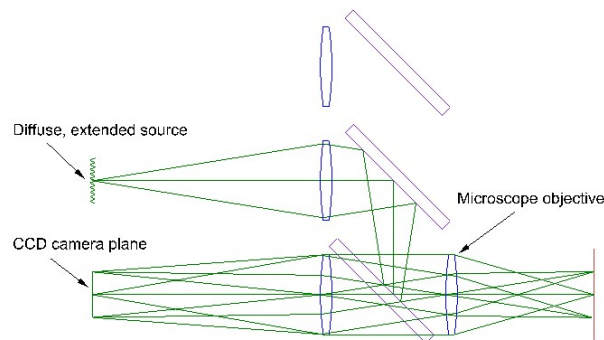
# A contemporary version of the ASM is three instruments in one



Autostigmatic microscope  
Internal SM fiber source



Electronic autocollimator  
Simply remove objective



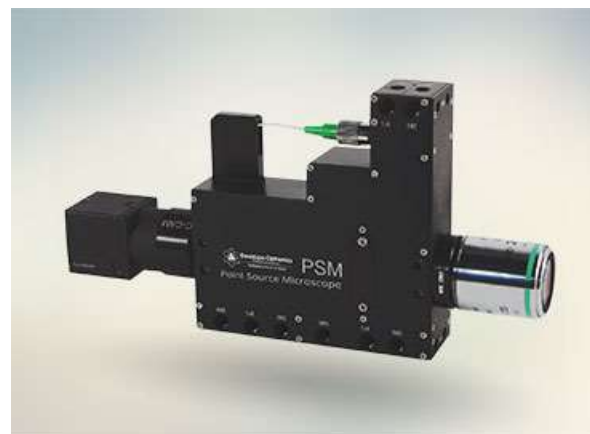
Video imaging microscope  
Image plane para focal with ASM focus  
Internal LED Kohler source





# Some advantages of the contemporary design

- Use of solid state light sources – compact, internal, low heat, monochromatic
- SM fiber coupled laser diode – bright for ease of alignment, near perfect spot
- Video camera – ergonomic, high position sensitivity, settable reference
- Software – permits high resolution centroiding on reflected spot
  - Large dynamic range on reflected light intensities
  - Recording and storage of Star images for optical quality determination
  - Centroid data easily coupled into other scales, a CMM, for example



# Other uses of the ASM; designed for alignment

Perfect for locating centers of curvature and foci of optical systems

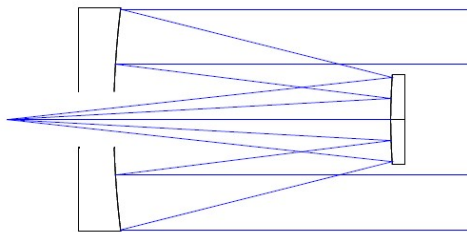
Use as a sensor on a centering station using a rotary table to define an axis

Use was to align the elements of a f-theta laser scanner lens to a common axis

Lens system had spherical and toroidal lenses and an “off-axis” mirror

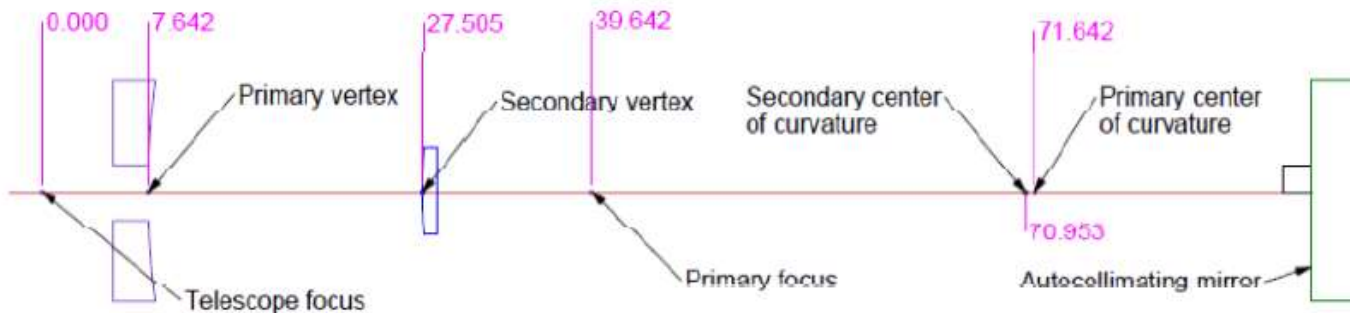
ASM mounted to the ram of a coordinate measuring machine

Used as a large x, y, z stage to pick up centers of curvature and align to axis

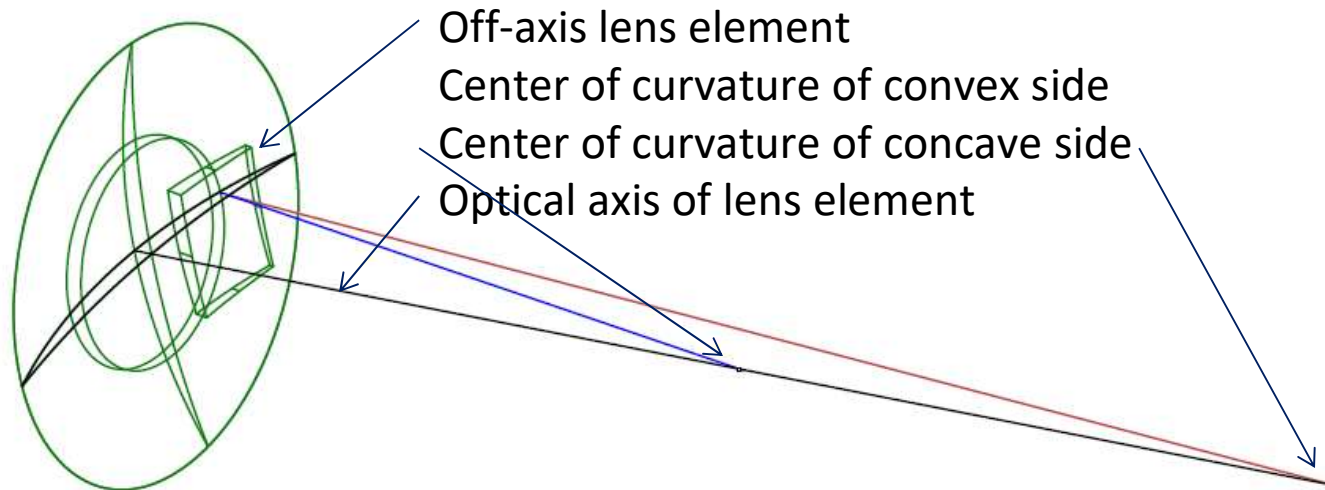


Don't think like a lens designer and where rays go

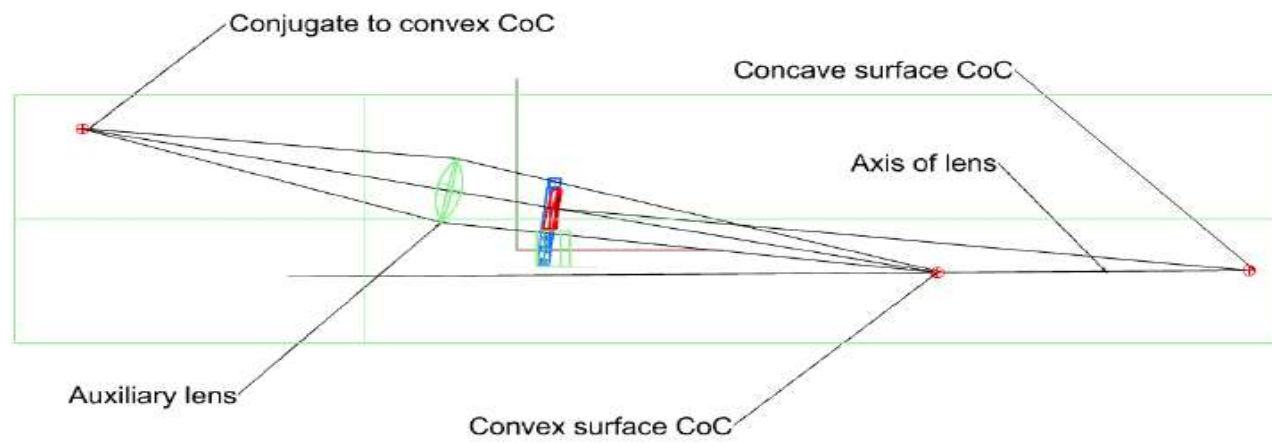
Think about where centers of curvature should go and how to get them on a common axis



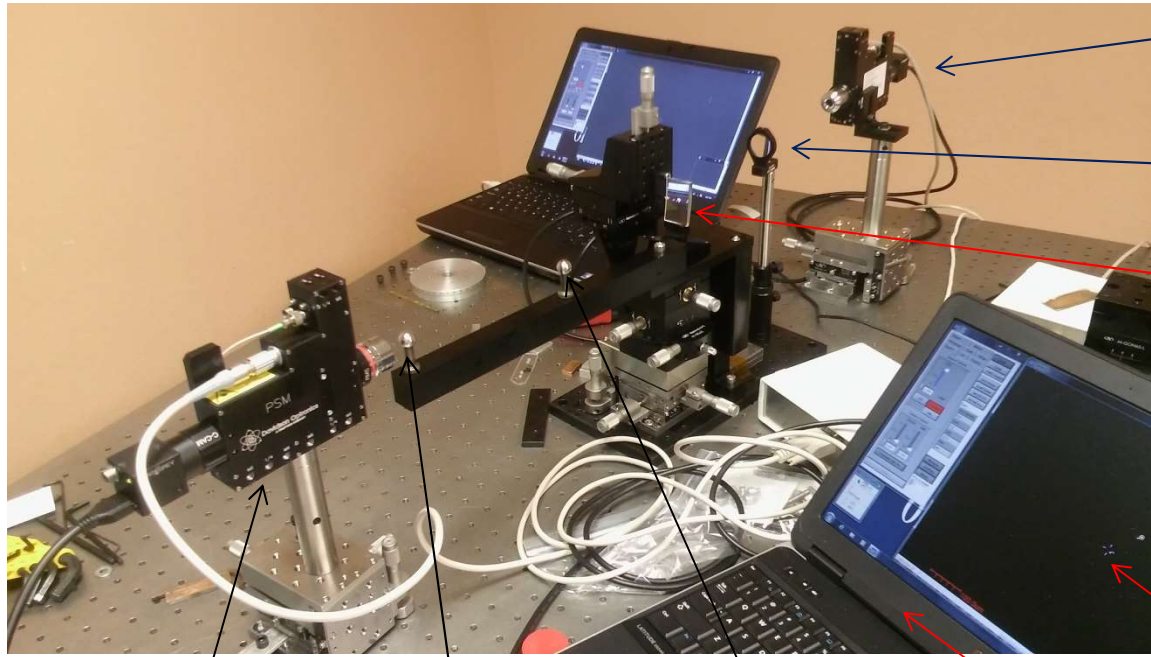
# Use two ASM's to align an "off-axis" lens



Radius of convex side longer than working distance of objective, need extra lens



# Set-up using 2 ASM's to align lens



First PSM

Auxiliary lens

"Off-axis" lens

Return spot from ball

Crosshairs

Second PSM

Ball at CC CofC

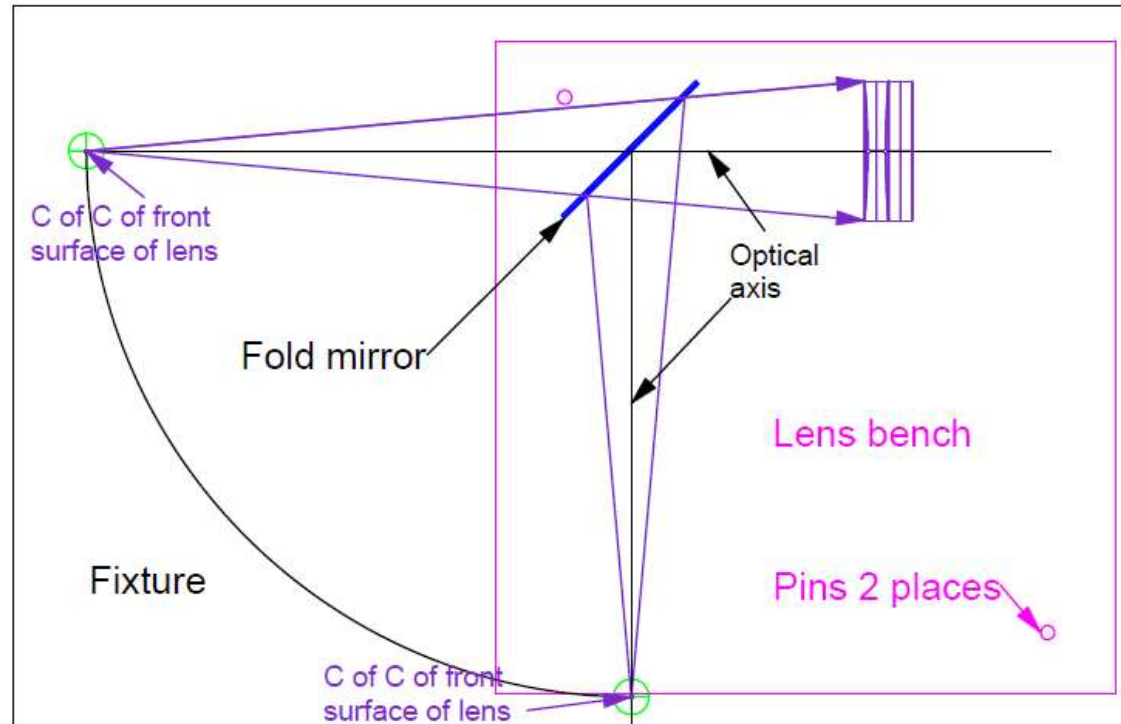
Ball at CX CofC

Laptop for 2<sup>nd</sup> PSM

Once set up the alignment took a couple of minutes  
Time savings in production would be immense



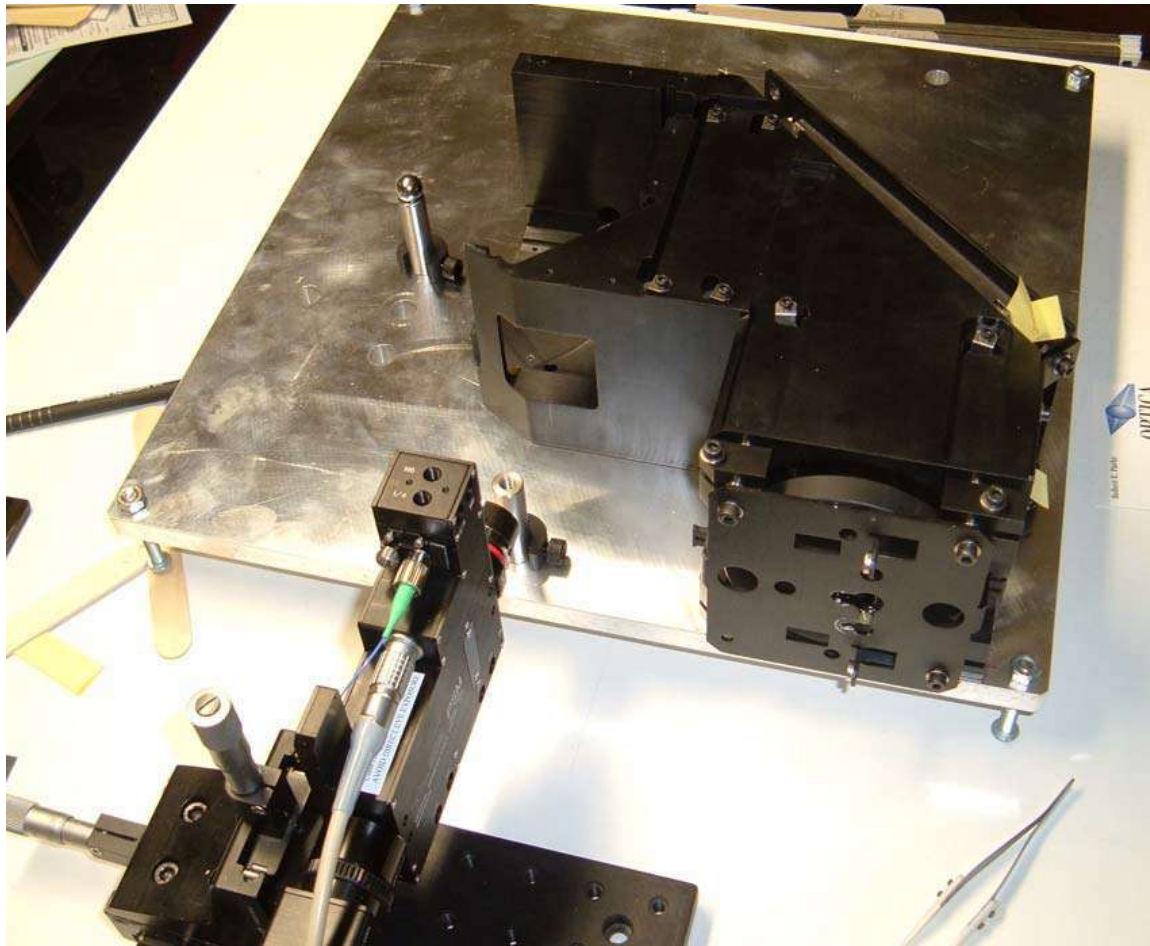
# Alignment of fold mirrors



Plane fold mirrors have 3 degrees of freedom, 2 tilt and one displacement  
Optical and mechanical design will show where the center of curvature should be located when the fold mirror is proper aligned  
A ball in a fixture will mechanically locate this position, and ASM can verify



# Another example of a fixture for alignment



# The role of steel balls in alignment

*Steel balls are a physical realization of a point in space*

Something you can physically touch as opposed to a theoretical object

The ball center, the “point”, defines 3 translational degrees of freedom in space

The ASM transfers an optical point, a CofC or focus, something you cannot touch,  
to the center of a ball, something that can be located physically

Steel balls are inexpensive, extremely precise and come in many sizes

Grade 5 chrome steel balls are round to 125 nm and cost about \$3 each

Can be thought of as convex optical grade mirrors

Plug gauges are the cylindrical equivalent of balls and define axes in 3 DofF

(Plug gauges are Go/no go pins for gauging the size of holes)



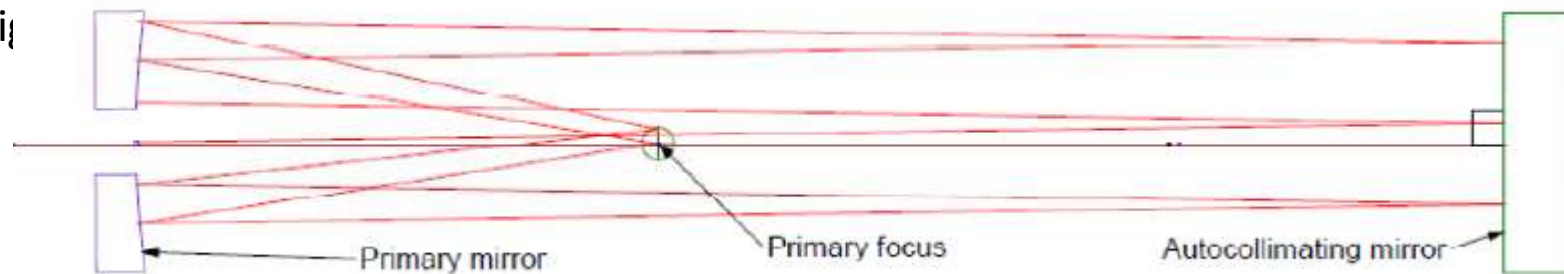
# Alignment using aberrations

An ASM is a “Star” test device showing the point spread of an aberrated wavefront

It has sensitivity to about  $\lambda/8$  or  $\lambda/10$

Useful for quick check of quality of optical surfaces as they are assembled into systems

Aliq



Initially the return spot will not be centered on the crosshairs of the ASM

The parabola or autocollimating mirror are tilted until return spot on crosshairs



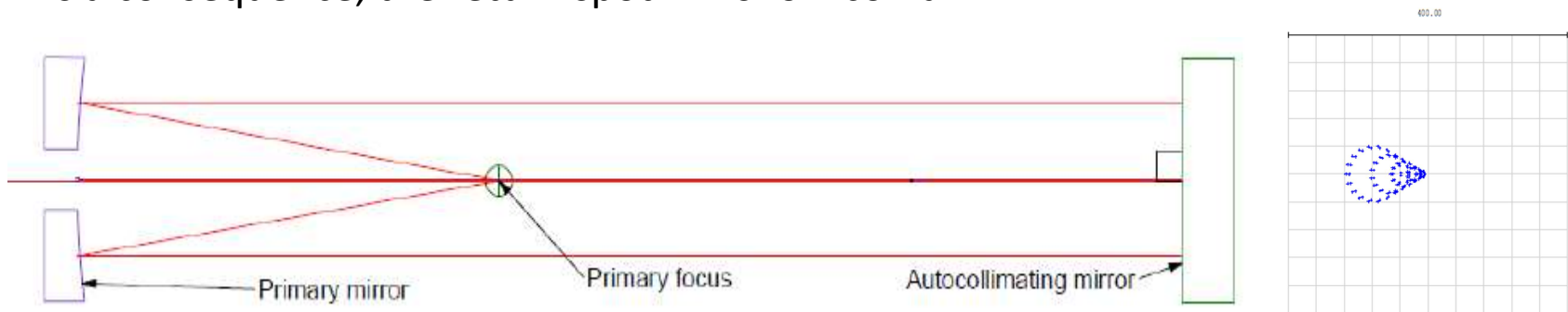


# Alignment using aberrations (con't)

When return spot lies on the crosshairs, the rays strike the flat at normal incidence

However, the normal to the flat may not be parallel to axis of parabola

As a consequence, the return spot will show coma



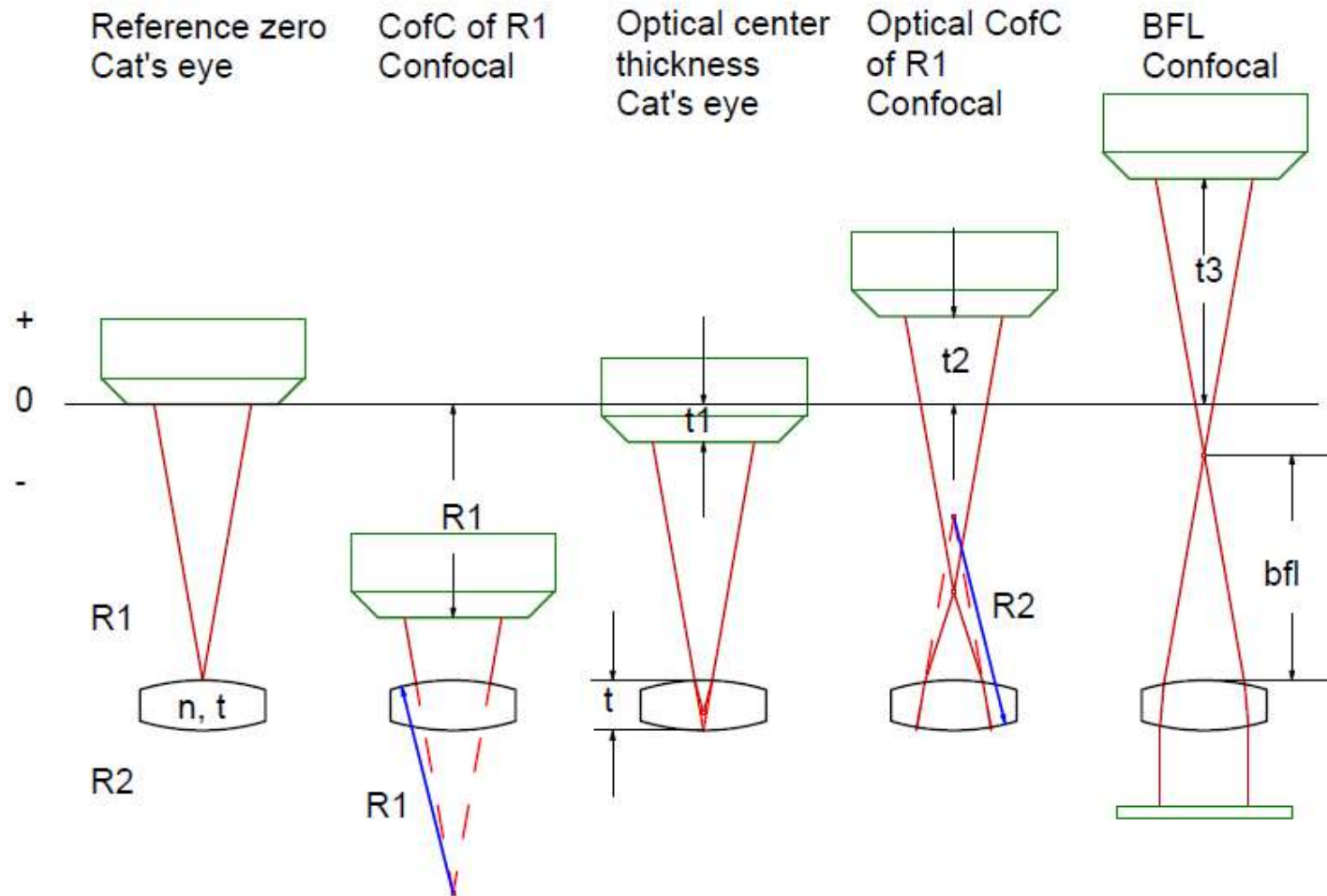
Simulated point spread of coma

To finish the alignment, tilt the flat while keeping return spot on the crosshairs until the coma is reduced to a symmetrical spot.

The entire alignment process takes only minutes to accomplish



# Other uses of an ASM – Finding lens conjugates



# Finding first order lens conjugates

Finding the radius of curvature of one side is direct measurement

This assumes it is concave or there is sufficient working distance

Almost any lens can be reversed and measured through the opposite side if not enough working distance

To find the other conjugates it is necessary to model with a lens design program

Or use first order equations and an iterative equation solving program

See Parks, R. E., "Measuring the four paraxial...", *Appl. Opt.*, **54**, 9284 (2015)



# Zero index material – a useful trick

When using an ASM or an interferometer most setups are double pass

Light comes from the instrument, reflects at normal incidence off the last surface and retraces itself back into the instrument

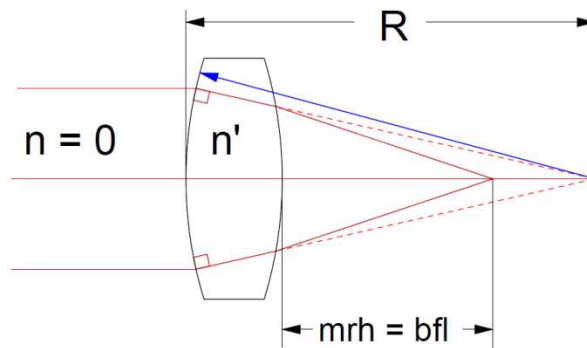
For a quick insight to the test it is a lot of work to trace a double pass system

The trick; reverse the system and make rays leave the last surface at normal incidence

To do this have rays from infinity travel through a medium of 0 index to the last surface

Then  $n \cdot \sin(\theta) = n' \cdot \sin(\theta') = 0$ , so  $\theta' = 0$ , or the rays leave the last surface normal to it!

Now a marginal ray height solve after the last refraction shows the paraxial focus



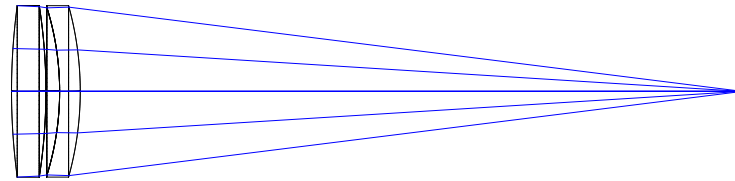
Credit for the idea; I don't know who deserves it  
I learned it from Jim Burge at UofA, Optical Sciences  
I suspect he may have learned it from Roland Shack  
If someone knows a better attribution I like to know.



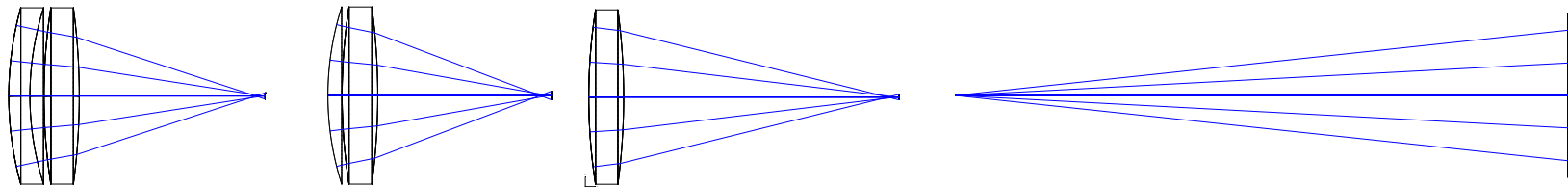
# An example – finding CofC's and surfaces vertices looking into the system

Assume a simple optical system such as an air spaced doublet

Find the centers of curvature and surfaces vertices looking into the system



Reverse elements, object at infinity and  $n = 0$ , float by stop on last surface



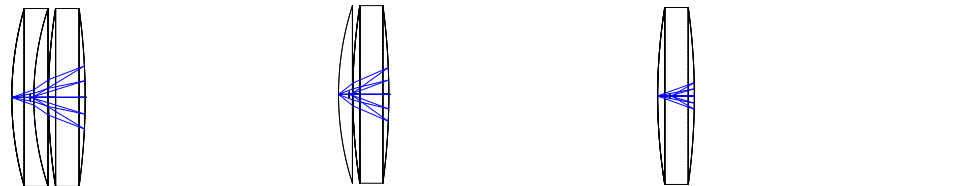
MRH = 26.403

= 24.395

= 39.445

= -94.453

Object on first surface, image space  $f/\#$  large, stop on last surface



MRH = -7.471

= -5.492

= -3.368

= 0

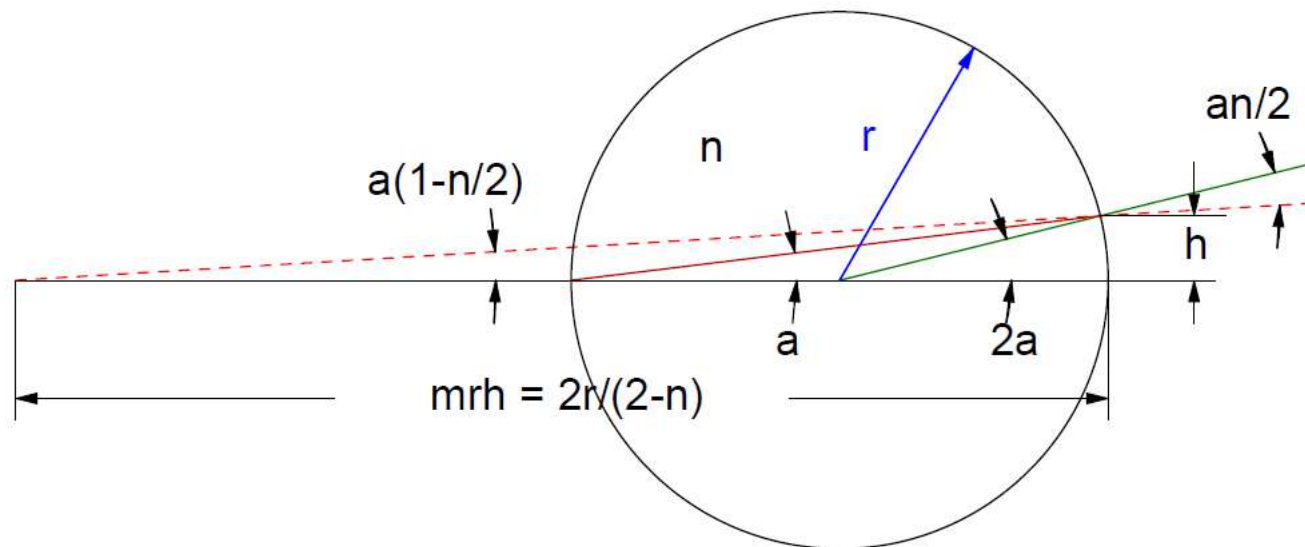


# Find the index of refraction of a ball

For small angles  $a = h/2r$ , and the normal =  $2a$ , so the refracted ray angle is  $an/2$

The ray angle relative to the x axis is  $2a - an/2 = a(1-n/2)$

The  $mrh = h/(h/r(1-n/2)) = 2r/(2-n)$

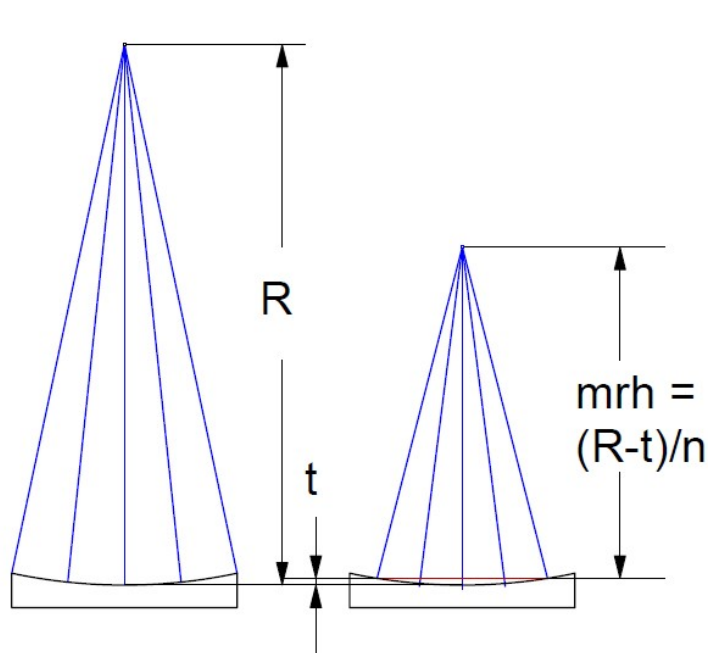


Or,  $n = 2(mrh - r)/mrh$

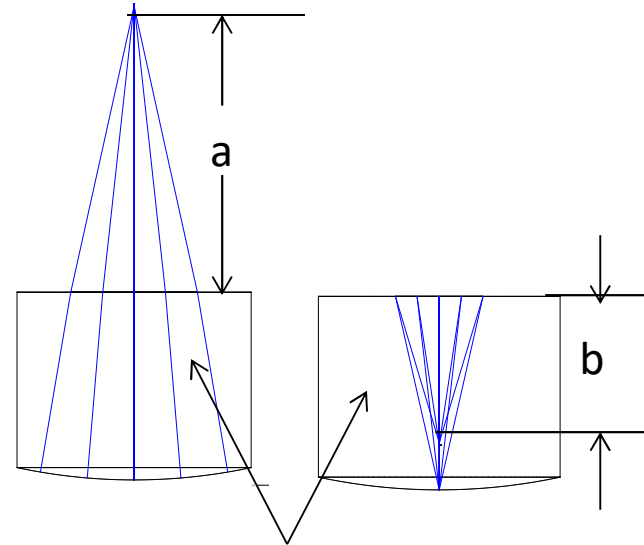
Works even if ball behind a window in a thermal chamber, but use ray trace



# Find the index of a liquid and radius of a submerged surface



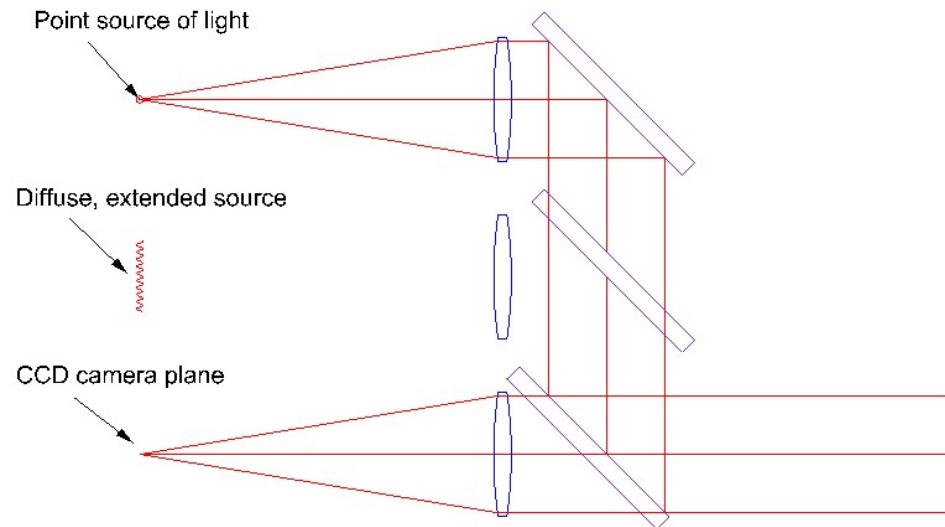
Concave mirror with radius  $R$ , left  
 Mirror with liquid index  $n$ , right  
 $n = (R - t)/mrh$ ,  $t =$  liquid thickness  
 Liquid is plano-convex lens



Liquid of index  $n$ , must be known  
 Measure  $a$  and  $b$  relative surface of liquid  
 The liquid thickness  $t = b * n$ ,  
 and  $a = (R/n) - b$ , so  $R = (a + b) * n$



# Measurement of angle



As shown earlier, by simply removing the objective the ASM is an autocollimator with sub-arc second sensitivity

The bright mode of the laser source makes initial alignment easy in ambient light

The small beam size makes it particularly useful for inspecting small prisms





# ASM's and computer generated holograms

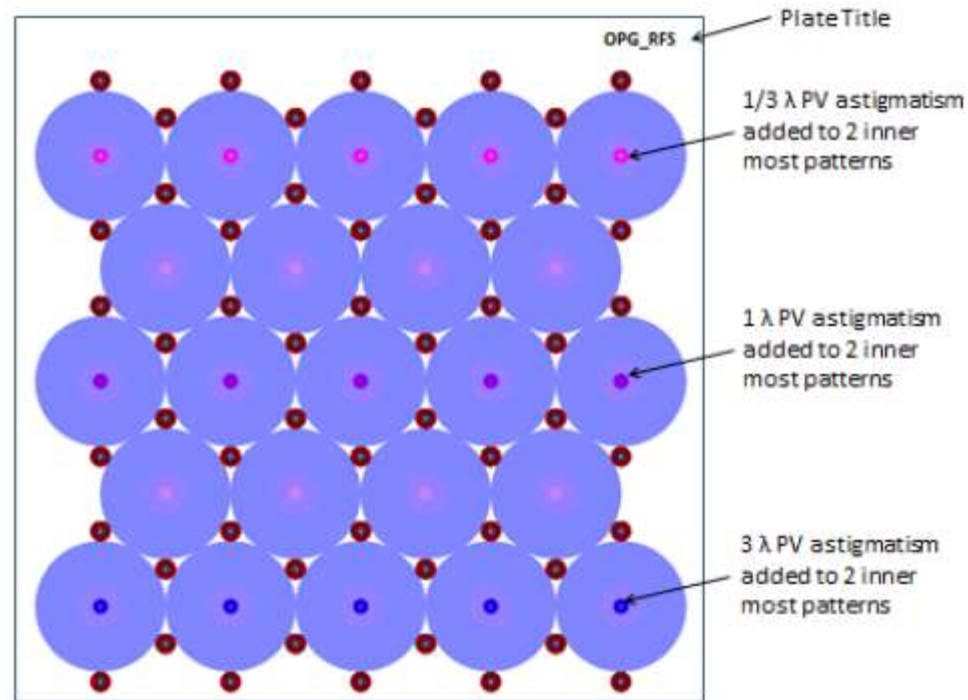
A CGH pattern can simulate a ball, that is focus light a specific distance above the CGH  
If balls are used to kinematically locate a CGH, a pattern to locate the balls can be included as part of the overall pattern. Then an ASM can precisely locate the balls.  
The balls, cemented in place, become an integral part of the CGH test artifact.

Because a CGH pattern can simulate a ball, a CGH can be made as an artifact for locating a group of points in space precisely located to  $< 1 \mu\text{m}$  in 3 dimensions.

An ASM mounted on a robot arm, for example, could be used to pick up the points one at a time to train and calibrate the robot.



# Example of CGH hologram



Printed on a 150 mm square photomask substrate

Each circular pattern produces points several distances above the CGH

Actual photograph is not available at the moment

CGH courtesy of Arizona Optical Metrology, LLC, [www.cghnulls.com](http://www.cghnulls.com)



# Conclusions

While autostigmatic microscopes (ASM) are over 100 years old, modern technology makes them truly practical for many diverse optical metrology needs.

Once the basic operation of measuring the radius of curvature with an ASM is understood, it becomes obvious that an ASM has many more useful applications.

Almost everything discussed here can also be done with an interferometer with greater precision. However, if the ultimate in precision is not needed the ASM is more convenient to use because of its small size, light weight and ease of mounting. Further, in some applications the greater coherence of an interferometer make some of the applications more difficult to perform because of multiple fringe patterns.

In many instances an ASM is a cost effective and easy to use alternative to an interferometer.

